

Existence Theorem for Semilinear Impulsive Functional Differential Equations with Nonlocal Conditions

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Abstract—The existence, uniqueness and continuous dependence of a mild solution of a Cauchy problem for semilinear impulsive first and second order functional differential equations with nonlocal conditions in general Banach spaces are studied. Methods of fixed point theorems, of a C_0 semigroup of operators and the Banach contraction theorem are applied.

Index Terms—Functional-differential equations, impulsive, mild solution, nonlocal conditions, semilinear.

I. INTRODUCTION

Many evolutionary processes in nature are characterized by the fact that at certain moments of time they experience an arbitrary change of the states. Therefore, the theory of impulsive differential equations is richer than that of the corresponding non-impulsive differential equations and repeats its development (see monographs [1], [2]). The theory of impulsive differential equations is quite new and is one of the attractive branches of differential equations which has extensive realistic mathematical modeling applications in physics, chemistry, engineering, and biological and medical sciences. The nonlocal condition is a generalization of the classical initial condition. A Banach space is a normed linear space that is a complete metric space with respect to the metric derived from its norm [3], [4]. A normed linear space is a metric space with respect to the metric d derived from its norm, $d(x, y) = \|x - y\|$. If (X, d) is a metric space, then a contraction of X (also called contraction on X) is a function $f: X \rightarrow X$ that satisfies

$$\forall x, x' \in X: d(f(x), f(x')) \leq \alpha d(x, x')$$

for some real number $\alpha < 1$. Such an α is called a contraction modulus of f . Every contraction mapping on a complete metric space has a unique fixed point. (This is also called the Contraction Mapping Theorem.) If T is a contraction on a complete metric space (X, d) and α is a contraction modulus of T , then for every $x \in X$,

$$\forall n \in \mathbb{N}: d(T^n x, x^*) \leq \alpha^n d(x, x^*),$$

Manuscript received January 9, 2013; revised March 14, 2013.

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where x^* is the unique fixed point of T . The generator A of a C_0 semigroup U is the operator

$$Ax := \lim_{h \rightarrow 0} \frac{1}{h} (U^h - 1)x,$$

defined for all those $x \in X$ for which this limit exists. Generally speaking, we say that a C_0 semigroup is a strongly continuous one parameter semi-group of bounded linear operators on a Banach space X . A C_0 semigroup (or strongly continuous semigroup) is a family $T = \{T(t) | t \in \mathbb{R}^+\}$ of bounded linear operators from X to X satisfying $T(t + s) = T(t)T(s) \forall t, s \in \mathbb{R}^+$, secondly, $T(0) = I$ — the identity operator on X and, finally, $\lim_{t \rightarrow 0^+} T(t)f = f$ for each $f \in X$ with respect to the norm on X . In this paper we study the existence, uniqueness and continuous dependence of a mild solution of a nonlocal Cauchy problem for a semilinear impulsive functional-differential evolution equation. Such problems arise in some physical applications as a natural generalization of the classical initial value problems. We cannot measure $x(t_0)$ and $x(t_k)$, ($k=1, 2, \dots, p$) but we can measure a relation between measure $x(t_0)$ and $x(t_k)$, ($k=1, 2, \dots, p$). There are some physical problems where nonlocal conditions are more realistic and useful than the classical initial conditions such as theory of vibrations, kinematics to determine the evaluation of $t \rightarrow x(t)$ of the location of a physical object for which we do not know the positions $x(t_0), x(t_1), \dots, x(t_p)$, but we do know that the introduced suitable nonlocal condition is satisfied. For example following nonlocal model describes simultaneous description of the motion trajectories $t \rightarrow x(t)$ of two rockets. The first rocket is launched to the cosmic space from the Earth's surface outside of the Earth's gravitation and the second rocket is launched from Earth orbit and next rocket goes to the cosmic space in the same direction as the first rocket [8].

$$\begin{cases} \dot{x}(t) + A(t)x(t) = f(t, x(t)), & t \in [0, T], \\ x(t) = M e^{\beta t_0} x(t + T^*), & t \in [-r, 0], T^* \in [t_0 + r, T] \end{cases}$$

The result shows that for each time $T^* \in [t_0 + r, T]$ and delay $\tau \in [-r, 0]$ there exist a unique initial location $\varphi_*(\tau)$ of the rocket which is having unique orbit and there is only one motion trajectory $t \rightarrow x_*(t); t \in [-r, T]$ of the rocket. For $t \rightarrow \infty$ all the motion trajectories $t \rightarrow x_\varphi(t)$ of the rocket, corresponding to the local problem will tend exponentially to the trajectory $t \rightarrow x_*(t)$.

The results for a semilinear functional-differential evolution nonlocal problem [5]-[7] are extended for the case

of impulse effect.

We consider a nonlocal Cauchy problem in the form

$$\begin{cases} \dot{u}(t) + Au(t) = f(t, u(t), u(b_1(t)), \dots, u(b_m(t))), \\ t \in (t_0, t_0 + a], \quad t \neq \tau_k, \\ u(\tau_k + 0) = Q_k u(\tau_k) \equiv u(\tau_k) + I_k u(\tau_k), \quad k = 1, 2, \dots, \kappa, \\ u(t_0) = u_0 - g(u), \end{cases} \quad (1)$$

where $t_0 \geq 0$, $a > 0$ and $-A$ is the infinitesimal generator of a compact C_0 semigroup of operators on a Banach space E . I_k ($k = 1, 2, \dots, \kappa$) are linear operators acting in the Banach space E . The functions f, g, b_i ($i = 1, 2, \dots, m$) are given satisfying some assumptions and u_0 is an element of the Banach space E . $I_k u(\tau_k) = u(\tau_k + 0) - u(\tau_k - 0)$ and the impulsive moments τ_k are such that $t_0 < \tau_1 < \tau_2 < \dots < \tau_k < \dots < \tau_\kappa < t_0 + a$, $\kappa \in \mathbb{N}$.

Theorems about the existence, uniqueness and stability of solutions of differential and functional-differential abstract evolution Cauchy problems were studied in [8], [9]. The results presented in this paper are a generalization and a continuation of some results reported in [10], [11]. We consider a classical semilinear impulsive functional-differential equation in the case of a nonlocal condition, reduced to the classical impulsive initial functional value problem. So far there have been a limited number of papers in this direction studying the existence of solutions of second order impulsive differential equations with nonlocal conditions. We try to extend the results of first order impulsive differential equations to second order impulsive differential equations with nonlocal conditions.

As usual, in the theory of impulsive differential equations [6], at the points of discontinuity τ_i of the solution $t \mapsto u(t)$ we assume that $u(\tau_i) \equiv u(\tau_i - 0)$. It is clear that, in general, the derivatives $\dot{u}(\tau_i)$ do not exist. On the other hand, according to the first equality of (1) there exist the limits $\dot{u}(\tau_i \mp 0)$. According to the above convention, we assume $\dot{u}(\tau_i) \equiv \dot{u}(\tau_i - 0)$ [1], [2].

Throughout the paper we assume that E is a Banach space with norm $\|\cdot\|$, $-A$ is the infinitesimal generator of a C_0 semigroup $\{T(t)\}_{t \geq 0}$ on E , $D(A)$ is the domain of A [11]. A C_0 semigroup $\{T(t)\}_{t \geq 0}$ is said to be a compact C_0 semigroup of operators on E if $T(t)$ is a compact operator for every $t > 0$. We denote

$$I := [t_0, t_0 + a], \quad M := \sup_{t \in [0, a]} \{ \|T(t)\|_{BL(E, E)} \}$$

and X is the space of piecewise continuous functions $I \rightarrow E$ with discontinuities of the first kind at $\tau_1, \tau_2, \dots, \tau_\kappa$.

Let $f: I \times E^{m+1} \rightarrow E$, $g: X \rightarrow E$ (for instance, we can have

$$g(u) = \tilde{g}(u(t_1), u(t_2), \dots, u(t_p)),$$

where

$\tilde{g}: E^p \rightarrow E$, $t_0 < t_1 < t_2 < \dots < t_p < t_0 + a$, $p \in \mathbb{N}$, $b_i: I \rightarrow I$ ($i = 1, 2, \dots, m$) and $u_0 \in E$. In these sequel, the operator norm $\|\cdot\|_{BL(E, E)}$ will be denoted by $\|\cdot\|$. We need the following sets:

$$E_\rho := \{z \in E, \|z\| \leq \rho\} \quad \text{and} \quad X_\rho := \{w \in X, \|w\|_X \leq \rho\},$$

$\rho > 0$.

Introduce the following assumptions [6]:

A1: $f \in C(I \times E^{m+1} \rightarrow E)$, $g \in C(X, E)$ and $b_i \in C(I, I)$, $i = 1, 2, \dots, m$ and there are constants C_i , $i = 1, 2, 3$, such that

$$\begin{cases} \|f(s, z_0, z_1, \dots, z_m)\| \leq C_1 \text{ for } s \in I, \\ z_i \in E_r (i = 0, 1, \dots, m), \\ \|g(w)\| \leq C_2 \text{ and } \max_{k=1,2,\dots,\kappa} \|I_k w\| \leq C_3 \text{ for } w \in X_r, \\ \text{where } r := M(aC_1 + \|u_0\| + C_2 + \kappa C_3). \end{cases} \quad (2)$$

A2: $g(\lambda w_1 + (1 - \lambda)w_2) = \lambda g(w_1) + (1 - \lambda)g(w_2)$ for $w_i \in X_r$, $i = 1, 2$, and $\lambda \in (0, 1)$, and r is given by (2).

A3: The set $\{w(t_0) = u_0 - g(w) : w \in X_r\}$, where r is given by (2), is precompact in E .

Consider the initial value problem [8]

$$\begin{cases} \dot{u}(t) + Au(t) = f(t), \quad t \in (t_0, t_0 + a], \\ u(t_0) = x, \end{cases} \quad (3)$$

where $f: I \rightarrow E$, $-A$ is the infinitesimal generator of a C_0 semigroup $T(t)$, $t \geq 0$, and $x \in E$.

Definition 1. A function u is said to be a *strong solution* of problem (3) on I if u is differentiable almost everywhere (a.e.) on I , so that $(du/dt) \in L^1((t_0, t_0 + a); E)$, $u(t_0) = x$ and $\dot{u}(t) + Au(t) = f(t)$ a.e. on I .

The unique strong solution u on I is given by the formula

$$u(t) = T(t - t_0)x + \int_{t_0}^t T(t - s)f(s) ds, \quad t \in I. \quad (4)$$

Definition 2. A function u is said to be a *classical solution* of problem (3) on I if u is continuous on I and continuously differentiable on $t \in (t_0, t_0 + a]$, such that $u(t) \in D(A)$ for $t_0 < t \leq t_0 + a$ and the problem (3) is satisfied on I .

If E is a Banach space and $-A$ is the infinitesimal generator of a C_0 semigroup $T(t)$, $t \geq 0$, $f: I \rightarrow E$ is continuous on I and $x \in D(A)$, then the problem (3) has a classical solution u on I given by (4).

Next consider the initial value problem for the impulsive linear system

$$\begin{cases} \dot{u}(t) + Au(t) = f(t), \quad t \in (t_0, t_0 + a], \quad t \neq \tau_k, \\ u(\tau_k + 0) = u(\tau_k) + I_k u(\tau_k), \quad k = 1, 2, \dots, \kappa, \\ u(t_0) = x, \end{cases} \quad (5)$$

where A, f and x are as in problem (3), and τ_k and I_k are as in problem (1).

Definition 3. A function $u: I \rightarrow E$ is said to be a *classical solution* of the problem (5) on I if u is piecewise continuous on I with discontinuities of the first kind at $\tau_1, \tau_2, \dots, \tau_\kappa$ and continuously differentiable on $(t_0, t_0 + a) \setminus \{\tau_k : k = 1, 2, \dots, \kappa\}$, such that $u(t) \in D(A)$ for $t_0 < t \leq t_0 + a$ and the problem (5) is satisfied on I .

If A, f and x are as above and $I_k: D(A) \rightarrow D(A)$, then the Problem (5) has a classical solution u on I given by the formula

$$\begin{aligned} u(t) = & T(t - t_0)x + \int_{t_0}^t T(t - s)f(s) ds \\ & + \sum_{t_0 \leq \tau_k < t} T(t - \tau_k)I_k u(\tau_k). \end{aligned} \quad (6)$$

Formula (6) motivates us to give the following definition.

Definition 4. A function $u \in X$ satisfying the following integro-summary equation

$$\begin{aligned} u(t) = & T(t - t_0)u_0 - T(t - t_0)g(u) \\ & + \int_{t_0}^t T(t - s)f(s, u(s), u(b_1(s)), \dots, u(b_m(s))) ds \\ & + \sum_{t_0 \leq \tau_k < t} T(t - \tau_k)I_k u(\tau_k), \quad t \in [t_0, t_0 + a], \end{aligned}$$

is said to be a *mild solution* of the nonlocal Cauchy problem (1).

II. EXISTENCE AND UNIQUENESS THEOREMS

Theorem 1. Suppose that assumptions A1-A3 are satisfied, then the impulsive nonlocal Cauchy problem (1) has a mild solution.

Proof. The mild solution of the impulsive system (1) with nonlocal condition satisfies the operator equation (6)

$$u(t) = (Fu)(t),$$

where

$$\begin{aligned} (Fw)(t) := & T(t - t_0)u_0 - T(t - t_0)g(w) \\ & + \int_{t_0}^t T(t - s)f(s, w(s), w(b_1(s)), \dots, w(b_m(s))) ds \\ & + \sum_{t_0 \leq \tau_k < t} T(t - \tau_k)I_k w(\tau_k), \quad t \in [t_0, t_0 + a], \end{aligned}$$

so that

$$\|(Fw)(t)\| \leq M\|u_0\| + MC_2 + aMC_1 + \kappa MC_3 = r,$$

where the impulsive moments τ_k are such that $t_0 < \tau_1 < \tau_2 < \dots < \tau_k < \dots < \tau_\kappa < t_0 + a$, $\kappa \in \mathbb{N}$. See detailed proof in [6].

Theorem 2. Suppose that the functions f, g and b_i ($i = 1, 2, m$) satisfy assumptions A1, A2, where $u_0 \in E$. Then in the class of all the functions w , for which assumption A3 holds, the nonlocal Cauchy problem (1) has a mild solution u . If in addition:

- 1) E is a reflexive Banach space,
- 2) there exists a constant $L > 0$ such that

$$\begin{cases} \|f(s, u_0, u_1, \dots, u_m) - f(\tilde{s}, \tilde{u}_0, \tilde{u}_1, \tilde{u}_m)\| \\ \leq L_1 \left(|s - \tilde{s}| + \sum_{k=0}^m \|u_k - \tilde{u}_k\| \right), \\ \|I_k v\|_E \leq L_2 \|v\|_E \text{ for } v \in E, \quad k = 1, 2, \dots, \kappa, \end{cases}$$

where $s, \tilde{s} \in I$, $u_i, \tilde{u}_i \in E_r$ ($i = 0, 1, 2, \dots, m$) and $L = \max\{L_1, L_2\}$.

- 3) u is the unique mild solution of the problem (1) and there is a constant $K > 0$ such that

$$\|u(b_i(s)) - u(b_i(\tilde{s}))\| \leq K \|u(s) - u(\tilde{s})\| \text{ for } s, \tilde{s} \in I,$$

- 4) The element $u_0 \in D(A)$ and $g(u) \in D(A)$,

then u is the unique classical solution of the impulsive nonlocal Cauchy problem (1).

Proof. Since all the assumptions of Theorem 1 are satisfied, then the nonlocal impulsive Cauchy problem (1) possesses a mild solution u which, according to assumption (iii), is the unique mild solution of the problem (1). Now, we will show that u is the unique classical solution of the semilinear, nonlocal, impulsive, Cauchy problem (1). Therefore,

$$\begin{aligned} u(t+h) - u(t) = & [T(t+h-t_0)u_0 - T(t-t_0)u_0] \\ & - [T(t+h-t_0)g(u) - T(t-t_0)g(u)] \\ & + \int_{t_0}^{t_0+h} T(t+h-s)f(s, u(s), u(b_1(s)), u(b_2(s)), \dots, u(b_m(s))) ds \\ & + \int_{t_0+h}^{t+h} T(t+h-s)f(s, u(s), u(b_1(s)), u(b_2(s)), \dots, u(b_m(s))) ds \\ & - \int_{t_0}^t T(t-s)f(s, u(s), u(b_1(s)), u(b_2(s)), \dots, u(b_m(s))) ds \\ & + \sum_{t_0 \leq \tau_k < t+h} T(t+h-\tau_k)I_k(u(\tau_k)) - \sum_{t_0 \leq \tau_k < t} T(t-\tau_k)I_k(u(\tau_k)). \end{aligned}$$

Consequently, by applying Gronwall's inequality we have

$$\begin{aligned} \|u(t+h) - u(t)\| & \leq (C_* h + MC_3 i(t, t+h)) \exp(aML(1+mK)). \end{aligned}$$

Thus $\|u(t+h) - u(t)\| \rightarrow 0$ as $h \rightarrow 0$, and u is Lipschitz continuous on each interval of continuity in I . The Lipschitz continuity of u on each interval of continuity in I combined with the Lipschitz continuity of f on $I \times E^{m+1}$ imply that the mapping $t \mapsto f(t, u(t), u(b_1(t)), \dots, u(b_m(t)))$ is Lipschitz continuous on each interval of continuity in I . This property, together with the assumptions of Theorem 2, implies that the linear Cauchy problem

$$\begin{aligned} \dot{v}(t) + Av(t) = & f(t, u(t), u(b_1(t)), \dots, u(b_m(t))), \\ & t \in I, \quad t \neq \tau_k, \\ v(\tau_k + 0) = & u(\tau_k) + I_k(u(\tau_k)), \quad k = 1, 2, \dots, \kappa, \\ v(t_0) = & u_0 - g(u), \end{aligned}$$

has a unique classical solution v such that

$$\begin{aligned} v(t) = & T(t - t_0)u_0 - T(t - t_0)g(u) \\ & + \int_{t_0}^t T(t - s)f(s, u(s), u(b_1(s)), \dots, u(b_m(s))) ds \\ & + \sum_{t_0 \leq \tau_k < t} T(t - \tau_k)I_k(u(\tau_k)), \quad t \in I. \end{aligned}$$

Consequently, u is the unique classical solution of the nonlocal impulsive Cauchy problem (1) (details of the proof in [6]).

III. CONTINUOUS DEPENDENCE OF A MILD SOLUTION ON THE INITIAL CONDITION

Theorem 3. Suppose that the functions f, g and $I(u)$ satisfy

the assumptions **A1–A3** and there exist constants μ_1, μ_2, μ_3 such that

- 1) $\|g(u) - g(\tilde{u})\| \leq \mu_1 \|u - \tilde{u}\|$,
 - 2) $\|f(s, u(s), \dots, u(b_m(s))) - f(s, \tilde{u}(s), \dots, \tilde{u}(b_m(s)))\| \leq \mu_2 \|u - \tilde{u}\|$,
 - 3) $\|I_k(u(\tau_k)) - I_k(\tilde{u}(\tau_k))\| \leq \mu_3 \|u(\tau_k) - \tilde{u}(\tau_k)\|$,
- where $u, \tilde{u} \in C(I, E)$. If u and $\tilde{u}$ are mild solutions of the problem (1) with the respective initial values $u_0, \tilde{u}_0$ and the constants μ_1 and $\mu = \max\{\mu_2, \mu_3\}$ satisfy the inequality

$$\mu_1 < \frac{\exp(-(t_0 + a)M\mu)(1 + M\mu)^{-\kappa}}{M},$$

then the following inequality holds [6]:

$$\|u(t) - \tilde{u}(t)\| \leq \frac{M \exp((t_0 + a)M\mu)(1 + M\mu)^\kappa}{1 - M\mu_1 \exp((t_0 + a)M\mu)(1 + M\mu)^\kappa} \|u_0 - \tilde{u}_0\|. \quad (7)$$

Proof. Assume that $u, \tilde{u}$ are mild solutions of problem (1). Then

$$\begin{aligned} & u(t) - \tilde{u}(t) \\ &= [T(t - t_0)(u_0 - \tilde{u}_0) - T(t - t_0)(g(u) - g(\tilde{u}))] \\ &+ \int_{t_0}^t T(t - s) [f(s, u(s), u(b_1(s)), \dots, u(b_m(s))) \\ &\quad - f(s, \tilde{u}(s), \tilde{u}(b_1(s)), \dots, \tilde{u}(b_m(s)))] ds \\ &+ \sum_{t_0 \leq \tau_k < t+h} T(t - \tau_k) [I_k(u(\tau_k)) - I_k(\tilde{u}(\tau_k))], \end{aligned}$$

where $t \in [t_0, t_0 + a]$. From **A1–A3** and the hypotheses of the theorem, and applying Gronwall's inequality we have

$$\|u(t) - \tilde{u}(t)\| \leq \{ \|u_0 - \tilde{u}_0\| + \mu_1 \|u - \tilde{u}\| \} M \exp((t_0 + a)M\mu)(1 + M\mu)^\kappa.$$

We can also write this inequality in the form

$$[1 - M\mu_1 \exp((t_0 + a)M\mu)(1 + M\mu)^\kappa] \|u(t) - \tilde{u}(t)\| \leq M \exp((t_0 + a)M\mu)(1 + M\mu)^\kappa \|u_0 - \tilde{u}_0\|.$$

For more details of the proof, you can see [6] and the references therein.

Remark 1. If $\mu_1 = \kappa = 0$, then inequality (7) is reduced to the classical inequality.

$$\|u(t) - \tilde{u}(t)\| \leq M \exp((t_0 + a)M\mu) \|u_0 - \tilde{u}_0\|,$$

This is a characteristic for the continuous dependence of the semilinear functional-differential evolution Cauchy problem with the classical initial condition.

IV. SECOND ORDER IMPULSIVE DIFFERENTIAL EQUATIONS WITH NONLOCAL CONDITIONS

Consider a second order semilinear nonlocal impulsive differential equation of the form

$$\begin{cases} x''(t) = Ax(t) + f(t, x(t), x'(t)), \\ \quad t \in J = [0, b], \quad t \neq t_k, \\ \Delta x|_{t=t_k} = I_k(x(t_k)), \quad k = 1, \dots, m, \\ \Delta x'|_{t=t_k} = \bar{I}_k(x(t_k), x'(t_k)), \quad k = 1, \dots, m, \\ x(0) + g(x) = x_0, \quad x'(0) = x_1, \end{cases} \quad (8)$$

where A is a linear operator from a real Banach space X into itself with the norm $\|\cdot\|$ and

$$x_0, x_1 \in X, \quad 0 = t_0 < t_1 < \dots < t_m < t_{m+1} = b,$$

$$\Delta x|_{t=t_k} = x(t_k^+) - x(t_k^-), \quad \Delta x'|_{t=t_k} = x'(t_k^+) - x'(t_k^-),$$

and f, g, I_k , and $\bar{I}_k$ ($k = 1, 2, \dots, m$) are given functions to be specified. Let A be the same linear operator as in (1).

We need the following assumptions [9], [10]:

H1: The operator A is the infinitesimal generator of a strongly continuous cosine family $\{C(t): t \in \mathbb{R}\}$ of bounded linear operators from X into itself defined by

$$Ax = \frac{d^2}{dt^2} C(t)x|_{t=0}, \quad x \in D(A), \quad A: X \supset D(A) \rightarrow X.$$

The associated sine family $\{S(t): t \in \mathbb{R}\}$ is defined by

$$S(t)x = \int_0^t C(s)x ds, \quad x \in X, t \in \mathbb{R}.$$

H2: The adjoint operator A^* is densely defined in X^* , that is, $D(A^*) = X^*$. It can be easily seen from these assumption that for some constant $M \geq 1$ and $\omega \geq 0$ we have

$$\|C(t)\| \leq M e^{\omega|t|} \text{ and } \|S(t)\| \leq M e^{\omega|t|}, \text{ for all } t \in \mathbb{R}.$$

Denote $J_0 = [0, t_1], J_k = (t_k, t_{k+1}]$, $J' = J \setminus \{t_k\}$, $k = 1, 2, \dots, m$, and define the class of functions $PC(J, X) = \{x: J \rightarrow X, x \in C(J_k, X), k = 0, 1, \dots, m \text{ and there exist } x(t_k^+), x(t_k^-), k = 1, 2, \dots, m, \text{ with } x(t_k) = x(t_k^-)\}$ and $PC^1(J, X) = \{x \in PC(J, X): x' \in C(J_k, X), k = 0, 1, 2, \dots, m \text{ and there exist } x'(t_k^+), x'(t_k^-), k = 1, 2, \dots, m, \text{ with } x'(t_k) = x'(t_k^-)\}$. It is clear that $PC(J, X)$ and $PC^1(J, X)$ are Banach spaces with respective norms

$$\begin{aligned} \|x\|_{PC} &= \max \left\{ \sup_{s \in J_k} \|x(s)\|, k = 0, 1, \dots, m \right\}, \\ \|x\|_{PC^1} &= \max \{ \|x\|_{PC}, \|x'\|_{PC} \}. \end{aligned}$$

Definition 5 [12]. A map $f: j \times X \times X \rightarrow X$ is said to be L^1 -Carathéodory if $f: (\cdot, \omega, v): J \rightarrow X$ is measurable for every $\omega, v \in X$, $f: (t, \cdot, \cdot): X \times X \rightarrow X$ is continuous for almost all $t \in J$ and for each $i > 0$ there exists $\alpha_i \in L^1(J, \mathbb{R}_+)$ such that for almost all $t \in J$.

$$\sup_{\|\omega\|, \|v\| \leq 1} \|f(t, \omega, v)\| \leq \alpha_i(t).$$

A function $x \in PC^1(J, X) \cap C^2(J', X)$ satisfying $x(t) \in D(A)$ for all $t \in J$ and (8) is called a classical solution of the system (8). Then we get

$$\begin{aligned} x'(t) &= C(t)x'(0) + \int_0^t f(s, x(s), x'(s)) ds \\ &+ \sum_{0 < t_k < t} [x'(t_k^+) - x'(t_k)], \quad \forall t \in J, \end{aligned} \quad (9)$$

and, therefore,

$$\begin{aligned} x(t) &= C(t)x_0 + S(t)x_1 + x_0 + x_1 t \\ &+ \sum_{0 < t_k < t} [x(t_k^+) - x(t_k)] \\ &+ \sum_{0 < t_k < t} [x'(t_k^+) - x'(t_k)](t - t_k) \\ &+ \int_0^t S(t - s)f(s, x(s), x'(s)) ds, \quad \forall t \in J. \end{aligned} \quad (10)$$

In fact, let us assume $t_k < t < t_{k+1}$ (here $t_0 = 0, t_{m+1} = b$). Using the successive iteration techniques on the intervals $[0, t_1], [t_1, t_2], \dots, [t_k^+, t]$ we have

$$\begin{aligned} x'(t_1) - x'(0) &= \int_0^{t_1} f(s, x(s), x'(s)) ds, \\ x'(t_2) - x'(t_1^+) &= \int_{t_1}^{t_2} f(s, x(s), x'(s)) ds, \\ &\vdots \\ x'(t) - x'(t_k^+) &= \int_{t_k^+}^t f(s, x(s), x'(s)) ds. \end{aligned}$$

Adding these, we get

$$\begin{aligned} x'(t) &= x'(0) + \int_0^t f(s, x(s), x'(s)) ds \\ &\quad + \sum_{0 < t_k < t} [x'(t_k^+) - x'(t_k)]. \end{aligned}$$

Similarly, we can get

$$x(t) = x(0) + \int_0^t x'(s) ds + \sum_{0 < t_k < t} [x(t_k^+) - x(t_k)] \quad (11)$$

and, using the equation (9) in (11), we get the result (10).

Assume the following additional assumptions are satisfied [12]:

H3: $f: J \times X \times X \rightarrow X$ is an L^1 -Carathéodory mapping.

H4: $I_k \in C(\cdot, X)$, $\bar{I}_k \in C(X \times X, X)$ and there are constants $d_k, \bar{d}_k$ such that $\|I_k(\omega_k)\| \leq d_k$, $\|\bar{I}_k(\omega, v)\| \leq \bar{d}_k$, $k = 1, 2, \dots, m$ for every $\omega, v \in X$.

H5: $g: PC(J, X) \rightarrow X$ is a continuous function and for some constant M , $\|g(x)\| \leq M$, for every $x \in PC(J, X)$.

H6: There exists a function $p \in L^1(J, \mathbb{R}_+)$ such that $\|f(t, \omega, v)\| \leq p(t)\psi(\|\omega\| + \|v\|)$ for a.e. $t \in J$ and every $\omega, v \in X$ where $\psi: [0, \infty) \rightarrow [0, \infty)$ is a nondecreasing continuous function satisfying the inequality

$$(b+1) \int_0^b p(s) ds < \int_c^\infty \frac{ds}{\psi(s)}$$

where the constant c can be determined as

$$c = \|x_0\| + M + (b+1)\|x_1\| + \sum_{k=1}^m [d_k + (b+1-t_k)\bar{d}_k]$$

Definition 6. Consider the following second order nonlocal problem [10]

$$\begin{cases} x''(t) = Ax(t) + f(t, x(t), x'(t)), t \in (0, T) \\ x(0) = x_0, x: [0, T] \rightarrow X, f: [0, T] \times X^2 \rightarrow X \\ x'(0) + \sum_{i=1}^p h_i x(t_i) = x_1, x_0, x_1 \in X, h_i \in \mathbb{R}, \\ (i = 1, 2, \dots, p), 0 < t_1 < t_2 < \dots < t_p \leq T \end{cases} \quad (12)$$

Then the function $x \in C^1((0, T], X)$ satisfying the integral equation

$$\begin{cases} x(t) = C(t)x_0 S(t)x_1 - S(t) \left(\sum_{i=1}^p h_i x(t_i) \right) \\ + \int_0^t S(t-s)f(s, x(s), x'(s)) ds, s \in [0, T] \end{cases}$$

is said to be a mild solution of the nonlocal Cauchy problem (12).

Theorem 4. Under the assumptions **H3-H6** the second order impulsive problem with nonlocal conditions (8) has at least one solution on the interval J .

Proof. Define the space $B = PC^1(J, X)$. We can show that the functional operator G defined by

$$\begin{aligned} Gx(t) &= C(t)(x_0 - g(x)) + tS(t)x_1 + \sum_{0 < t_k < t} I_k(x(t_k)) \\ &\quad + \sum_{0 < t_k < t} \bar{I}_k(x(t_k), x'(t_k))(t - t_k) \\ &\quad + \int_0^t (t-s)f(s, x(s), x'(s)) ds, t \in J, \end{aligned}$$

has a fixed point and this fixed point is the solution of the equation (8). For details of the proof, you can see [12] and the given references. It can be shown that $G: B \rightarrow B$ is a completely continuous operator. Let $B_i = \{x \in B: \|x\|_{PC^1} \leq i\}$, for some $i > 1$. G maps B_i into an equicontinuous family. To show this result, let $x \in B_i$, and $t, \bar{t} \in J$ satisfy $0 < t < \bar{t} \leq b$. Then we have

$$\begin{aligned} \|Gx(t) - Gx(\bar{t})\| &\leq (\bar{t} - t) \|x_1\| \\ &\quad + \sum_{t \leq t_k \leq \bar{t}} d_k + \sum_{0 < t_k < t} (\bar{t} - t) \bar{d}_k + \sum_{t \leq t_k < \bar{t}} (\bar{t} - t_k) \bar{d}_k \\ &\quad + \int_0^t (\bar{t} - t) \alpha_i(s) ds + \int_t^{\bar{t}} (\bar{t} - s) \alpha_i(s) ds. \end{aligned} \quad (13)$$

Similarly,

$$\begin{aligned} &\|(Gx)'(t) - (Gx)'(\bar{t})\| \\ &\leq \left\| \int_0^t f(s, x(s), x'(s)) ds - \int_0^{\bar{t}} f(s, x(s), x'(s)) ds \right\| \\ &\quad + \left\| \sum_{0 < t_k < t} \bar{I}_k(x(t_k), x'(t_k)) - \sum_{0 < t_k < \bar{t}} \bar{I}_k(x(t_k), x'(t_k)) \right\| \\ &\leq \int_t^{\bar{t}} \alpha_i(s) ds + \sum_{t \leq t_k < \bar{t}} \bar{d}_k. \end{aligned} \quad (14)$$

The right-hand sides of (13) and (14) are independent of x and approach zero when $\bar{t} \rightarrow t$, this means G maps B_i into an equicontinuous family of functions [12]. By using the Arzelà-Ascoli theorem $G: B \rightarrow B$ is compact. It can be easily shown that $G: B \rightarrow B$ is continuous. This completes the proof of the theorem.

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